

# Predicting profiles in LAPD mirror configurations

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### 1 The Large Plasma Device (LAPD)

- 19.7m long, 1m diameter
- $T_e \sim 5-10$  eV
- $n_e$  up to  $\sim 10^{13} \text{ cm}^{-3}$
- Flexible magnetic geometry — good for mirror studies
- 1 Hz shot rate** — up to 31 million shots per year (have 15m+ shots recorded right now)
- Hundreds of diagnostics ports
- Data-rich environment** — ideal for ML

**Built out data aggregation system**

**Probe diagnostics**

- Langmuir sweeps —  $T_e$
- Triple probe
  - isat**,  $T_e$ ,  $V_f$
- Light diodes (x5)
- Fast framing camera
- RGA partial pressures
- Flux probe
- isat**,  $V_f$  x2

**Fixed diagnostics**

- Thomson scattering
- Interferometers (x2)
- Light diodes (x5)
- Fast framing camera
- RGA partial pressures
- Axial magnetic field

**Machine state information (MSI)**

- Discharge current
- Discharge voltage
- Gas pressure
- RGA partial pressures
- Axial magnetic field

### 4 Training data were collected to predict Langmuir probe profiles

- Random machine configurations (~20), varied:**
  - B at cathode, 7 values (500-2000G)
  - B at mirror: 6 values (250-1500G)
  - B at midplane: 6 values (250-1500G)
  - Gas puffing fueling rate: 7 values
  - Discharge power: 9 values
- Parameters chosen using latin hypercube sampling
  - Guarantees every sampling bin gets at least one sample (unlike random uniform sampling)
- 200k shots with machine state and axial diagnostics
- 100k shots with probe data
- 50k shots with fast framing camera footage
- Intersection of above after cleaning: **30k examples**
- Barely enough for deep learning techniques
- Downsampling needed to ease data movement and keep model sizes small
- Downsampled to common sample rate of 2.5 kHz
- Fast camera considerably downsampled (spatially, 256x256 to 60x5 or 15x3)
- Total downsampling and cuts: ~2TB to ~6GB

**Example training discharge**

### 5 Accurately predicting isat time series and profiles

**Goal: predict isat profiles with NNs**

- Use a feedforward NN:
  - as a benchmark for a generative model
  - to determine compact architectures
  - to find most informative diagnostics
- Trained standard feed-forward NNs**
  - Inputs: all diagnostics, MSI, and probe position
  - Outputs: isat time series
- Testing different architectures because:
  - each have particular inductive biases
  - EBMs are difficult to train, want to figure out good architectures beforehand
  - Architectures trained: dense NNs and convolutional NNs (CNNs) so far — CNNs are smaller for similar performance
- Profiles and time series are harder to match in the gradient region**
  - Small changes in position lead to large changes in isat
  - Large fluctuation amplitudes
- Improving performance in gradient/edge:
  - may need higher resolution (in FFC)
  - use a more expressive model

**Neural network predictions**

### 2 Motivation

- Goal of this project: autonomously optimize LAPD mirror transport**
  - Requires a method of predicting required settings to yield particular discharge characteristics
  - Generative modeling (modeling a probability distribution) provides this ability  
→ **energy based models (EBMs)** are a good candidate as an LAPD surrogate
- Predicting requires training on lots of data  
→ **built out data collection pipeline** for auxiliary diagnostics and machine state information
- Data needs to be diverse and well diagnosed  
→ **collected LAPD data with Langmuir probe diagnostics in a variety of mirror configurations**
- Generative model needs a benchmark for (forward model-like) conditional sampling performance  
→ **trained an accurate feedforward neural network to predict ion saturation current time traces**

**General NN-based prediction questions**

- Does prediction accuracy change with downsampling?
- Which diagnostics are most important for predicting profiles and transport-related quantities?
- Can transport quantities be accurately predicted without spectral information?
- Does strictly physical interpretations of the data limit prediction ability?
- Which NN architectures are best suited to this task?

### 3 Training energy-based models for diagnostic reconstruction

**Energy based models (EBMs)**  $p(x) \sim e^{-E(x)}$   
define probability as:

A neural network assigns energy value to input data:

**Data  $\rightarrow$   $E$**

Learn to assign energy values to inputs

- the model is **generative** — learns an implicit probability distribution
- Trained by pushing energy down on data, up on samples (contrastive divergence)

**Learns the relationship between all input variables — can predict anything from anything**

- Conditional sampling is easy
- Solution to inverse problems are built-in
- Can fill in missing data
- Energies are additive: can easily combine models

In a high-variance (learned) approach:

- All effects accounted for in prediction
- Model has few preconceived notions

**Sample from models:** Langevin dynamics

$$\dot{x} = -\nabla E(x) + \sqrt{T}\mathcal{N}(0, 1)$$

Energy surface Gaussian process

Existing signals  $y \sim p(y | x)$

Missing signal

**Sampled discharge current (kA) vs time (ms)**

Scaling laws Theory work Learned EBM

Discrepancy modeling

Number of sampling steps

### 6 Nitty-gritty training details

**Architectures (SiLU activations):**

- Dense: 6 layers, 256 hidden units each
- CNN: 10 convolutions (over time); alternating 5 and 21 width-kernels; 16 channels, 2 dense layers. Time-constant data concatenated at each time point

**Hyperparameters**

- Adam, learning rate 3e-4, momentum 0.99
- No weight decay or any other regularization
- Batch size 128 (~185 batches)
- 1000 epochs; early stopping employed
- 80-20 train-test split + 500 validation shots

**Next steps for this prediction problem:**

- Try out recurrent NNs
- Want to figure out which diagnostics are most important → remove signals, see how performance degrades
- Remove all MSI data (only FFC)
- Remove only axial diagnostics
- Fast framing camera downsample size
  - Higher resolution seems to perform better, but needs further investigation
- Include diagnostics left out by this analysis (e.g., 288 GHz interferometer, Thomson scattering, diamagnetic loop)

### 7 Future work

- Perform traditional analysis of probe data to calculate particle flux and diffusivity and add to the dataset
- Find a lightweight but performant network architecture
- Process and include additional diagnostics in the dataset
- Determine the most informative diagnostics for predicting profiles
- Train an EBM to predict profiles and to find the machine configuration necessary for a given profile (the inverse problem)
- Optimize LAPD mirror configurations given an objective function

### 8 Summary

- Any arbitrary diagnostic can be reconstructed given others → paves the way for finding machine configurations required for given discharge characteristics
- A diverse dataset, well diagnosed dataset was created  
→ provides a seed for further parameter space exploration
- Profile prediction using feedforward neural networks work is possible and has decent prediction accuracy  
→ now have a benchmark for EBMs and have cheaper a method of finding good architectures and signal combinations